

# Universal Decoding for Source–Channel Coding With Side Information

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# Some Related Earlier Work

## Universal channel decoding

Goppa (1975); Csiszár & Körner (1981); Csiszár (1982); Ziv (1985); Merhav (1993); Liu & Hughes (1996); Feder & Lapidoth (1998); Lapidoth & Ziv (1998); Feder & Merhav (2002); Lomnitz & Feder (2012); Merhav (2013); ...

## Universal source decoding (Slepian–Wolf)

Csiszár & Körner (1981); Oohama & Han (1994); Draper (2004); Chen, He, Jagmohan & Lastras–Montaña (2008); Sarvotham, Baron & Baraniuk (2005); ...

## Universal joint source–channel decoding

Csiszár (1980).

# Background: Csiszár's Universal JSC Decoder

A DMS  $u \in \mathcal{U}^n$  is directly mapped into a channel input vector  $x[u] \in \mathcal{X}^n$  and fed into a DMS whose output  $y$  is used to decode  $\hat{u}$ .

The error exponent is **upper bounded** by

$$E^{\text{jsc}} \leq \min_R \left[ E^{\text{S}}(R) + E^{\text{C}}(R) \right],$$

where

$E^{\text{S}}(R)$  = the **source coding exponent** and

$E^{\text{C}}(R)$  = the **channel reliability function**.

The error exponent is **lower bounded** by

$$E^{\text{jsc}} \geq \min_R \left[ E^{\text{S}}(R) + E_r^{\text{C}}(R) \right],$$

where  $E_r^{\text{C}}(R)$  = the **random coding exponent**.

# Background: Csiszár's Universal JSC Decoder (Cont'd)

Some comments:

- An equivalent lower bound

$$E^{\text{jsc}} \geq \max_Q \min_{P', W'} \{D(P' \| P) + D(W' \| W | Q) + [I(X; Y') - H(U')]_+\},$$

where:  $P$  = source,  $Q$  = random coding distribution, and  $W$  = channel.

- Idea of upper bound: Each source type  $P'$  induces a **sub-code** at rate  $R = H(P')$ . Counting errors only **within** the worst sub-code.
- The bounds coincide when  $R^*$  of the former is above  $R_{\text{crit}}$ .

# Background: Csiszár's Universal JSC Decoder (Cont'd)

Comments (continued):

- $\Rightarrow$  for  $R^* \geq R_{\text{crit}}$ , errors within sub-codes dominate.
- Universal decoder – “generalized MMI”: asymptotically equivalent to

$$\hat{u} = \arg \max_u [\hat{I}_{x[u]y}(X; Y) - \hat{H}_u(U)].$$

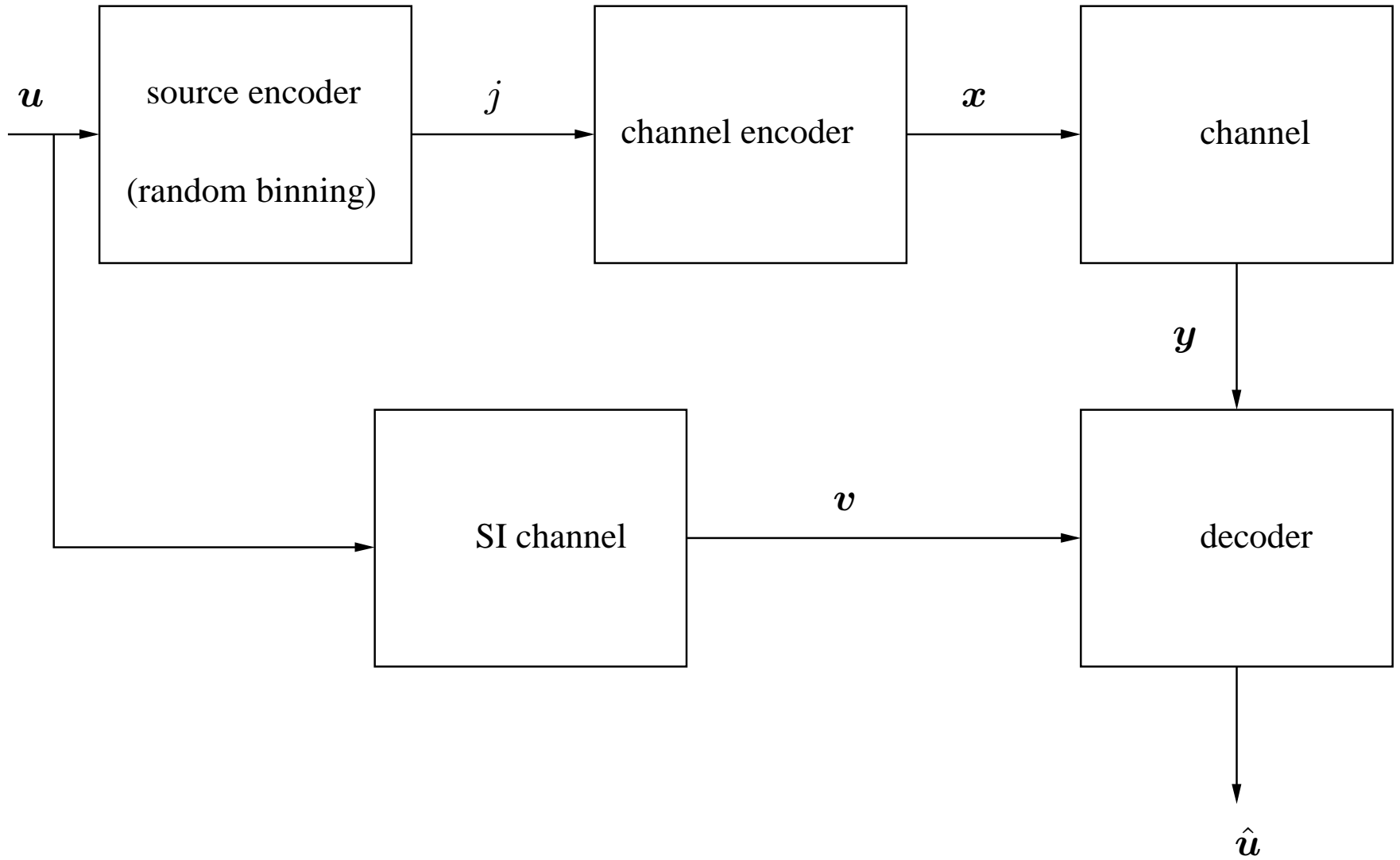
- GMMI is proved optimal for  $R \geq R_{\text{crit}}$ .
- Everything generalizes easily to bandwidth expansion factor  $\neq 1$ .

# Our Settings

We extend Csiszár's setting in several directions:

- Setting 1:
  - Availability of source side info @ decoder.
  - Slepian–Wolf source coding and channel coding.
- Setting 2: separate encodings + joint decoding of correlated sources.
- Further extensions:
  - FS sources/channels – universal decoding based on LZ coding.
  - Arbitrary sources/channels – universality w.r.t. classes of decoders.

# Setting 1



# Motivations

- Separate S–W source coding and channel coding:
  - A general framework – includes JSC as a special case.
  - May be dictated by system constraints: different units/locations, modularity, etc.
- A common framework for many important special cases:
  - Separate source– and channel coding without SI:  $v$  – degenerate.
  - Pure SW source coding: clean, large–alphabet channel  $y \equiv x$ .
  - Pure channel coding: source = BSS,  $v$  – degenerate.
  - Joint source–channel coding with/out SI: high binning rate.
  - Systematic coding.



# Formulation

We are given:

- A memoryless source pair  $\{(U_i, V_i)\}$ , with  $(U_i, V_i) \sim P$ :
  - $\mathbf{u} = (u_1, \dots, u_n)$  = source to be communicated.
  - $\mathbf{v} = (v_1, \dots, v_n)$  = side information @ decoder.
- A memoryless channel  $W(\mathbf{y}|\mathbf{x}) = \prod_t W(y_t|x_t)$ .
- Bandwidth expansion factor = 1 without essential loss of generality.

# Formulation (Cont'd)

Communication system:

- $u$  is mapped into a bin  $j = f(u)$  at rate  $R$  (selected at random).
- The bin is channel-coded into  $x[u] = x[f(u)]$  (random coding  $\sim \mathcal{T}(Q)$ ).
- The message  $u$  is estimated by  $\hat{u} = g(y)$ .
- The optimal MAP decoder

$$\hat{u} = \arg \max_{\mathbf{u}} P_{UV}(\mathbf{u}, \mathbf{v}) W(\mathbf{y} | \mathbf{x}[\mathbf{u}]).$$

Our goals are:

- Find the random-coding exponent of the MAP decoder,  $E(R, Q)$ .
- Find a universal decoder (ignorant of  $P$  and  $W$ ) that achieves  $E(R, Q)$ .

# Basic Result

## Theorem 1

1. The random-coding error exponent of the MAP decoder is given by (see also Chang 2011):

$$E(R, Q) = \min_{P_{U'V'}, W'} \{D(P_{U'V'} \| P_{UV}) + D(W' \| W|Q) + [R \wedge I(X; Y') - H(U'|V')]_+\}.$$

2. The universal decoders,

$$\hat{u} = \arg \max_{\mathbf{u}} [\hat{I}_{x[\mathbf{u}]y}(X; Y) - \hat{H}_{\mathbf{u}v}(U|V)]$$

and

$$\hat{u} = \arg \max_{\mathbf{u}} [R \wedge \hat{I}_{x[\mathbf{u}]y}(X; Y) - \hat{H}_{\mathbf{u}v}(U|V)]$$

both achieve  $E(R, Q)$ .

# Discussion

$$E(R, Q) = \min_{P_{U'V'}, W'} \{D(P_{U'V'} \| P_{UV}) + D(W' \| W|Q) + [R \wedge I(X; Y') - H(U'|V')]\}_+$$

- $E(R, Q)$  is monotonically non-decreasing, which is not trivial.
- When  $R$  is large enough, there is saturation – equivalence to JSC.
- For a clean, large alphabet channel, we recover the SW error exponent.

$$\hat{u} = \arg \max_{\mathbf{u}} [\hat{I}_{\mathbf{x}[\mathbf{u}]\mathbf{y}}(X; Y) - \hat{H}_{\mathbf{u}\mathbf{v}}(U|V)]$$

$$\hat{u} = \arg \max_{\mathbf{u}} [R \wedge \hat{I}_{\mathbf{x}[\mathbf{u}]\mathbf{y}}(X; Y) - \hat{H}_{\mathbf{u}\mathbf{v}}(U|V)]$$

- Decoder 1 is a natural extension of Csiszár's GMMI decoder.
- Decoder 2 has no apparent advantage, but later results will be related.

# A Word About the Analysis

- Exponentially tight analysis based on new techniques.
- Averaging for both random binning and random coding (one at a time).
- Lower bounding  $\overline{P_e}$  for the MAP decoder.
- Upper bounding  $\overline{P_e}$  for the universal decoders.
- Distinguishing between errors within the same bin and errors across bins.
- Error events are dominated by pairwise errors within the types.

# Extension – Finite–State Sources and Channels

Let the source be given by

$$P(\mathbf{u}, \mathbf{v}) = \prod_{t=1}^n P(u_t, v_t | s_t), \quad s_t = g(s_{t-1}, u_{t-1}, v_{t-1}).$$

Similarly, let the channel be given by

$$W(\mathbf{y} | \mathbf{x}) = \prod_{t=1}^n W(y_t | x_t, z_t), \quad z_t = h(z_{t-1}, x_{t-1}, y_{t-1}),$$

We have some technical assumptions on the random coding distribution  $Q(\mathbf{x})$ .

## Extension (Cont'd)

We use the notion of **conditional LZ compressibility** [Ziv 1985]: Given  $(\mathbf{x}, \mathbf{y}) = [(x_1, y_1), \dots, (x_n, y_n)]$ , apply LZ parsing to this sequence pair. Let

- $c(\mathbf{x}, \mathbf{y})$  = number of phrases.
- $c(\mathbf{y})$  = number of distinct phrases of  $\mathbf{y}$ .
- $\mathbf{y}(l)$  = the  $l$ th distinct  $\mathbf{y}$ -phrase,  $l = 1, 2, \dots, c(\mathbf{y})$ .
- $c_l(\mathbf{x}|\mathbf{y})$  = number of  $\mathbf{y}(l)$  in parsing of  $\mathbf{y}$ .

$$\hat{H}_{LZ}(\mathbf{x}|\mathbf{y}) = \frac{1}{n} \sum_{l=1}^{c(\mathbf{y})} c_l(\mathbf{x}|\mathbf{y}) \log c_l(\mathbf{x}|\mathbf{y}).$$

For example,  $n = 6$  and

$$\begin{aligned} \mathbf{x} &= 0 | 1 | 00 | 01 | \\ \mathbf{y} &= 0 | 1 | 01 | 01 | \end{aligned}$$

then

$$c(\mathbf{x}, \mathbf{y}) = 4, \quad c(\mathbf{y}) = 3, \quad \mathbf{y}(1) = 0, \quad \mathbf{y}(2) = 1, \quad \mathbf{y}(3) = 01,$$

$$c_1(\mathbf{x}|\mathbf{y}) = c_2(\mathbf{x}|\mathbf{y}) = 1, \quad c_3(\mathbf{x}|\mathbf{y}) = 2.$$

## Extension (Cont'd)

We also define

$$\hat{I}_{\text{LZ}}(\mathbf{x}; \mathbf{y}) = -\frac{\log Q(\mathbf{x})}{n} - \hat{H}_{\text{LZ}}(\mathbf{x}|\mathbf{y}),$$

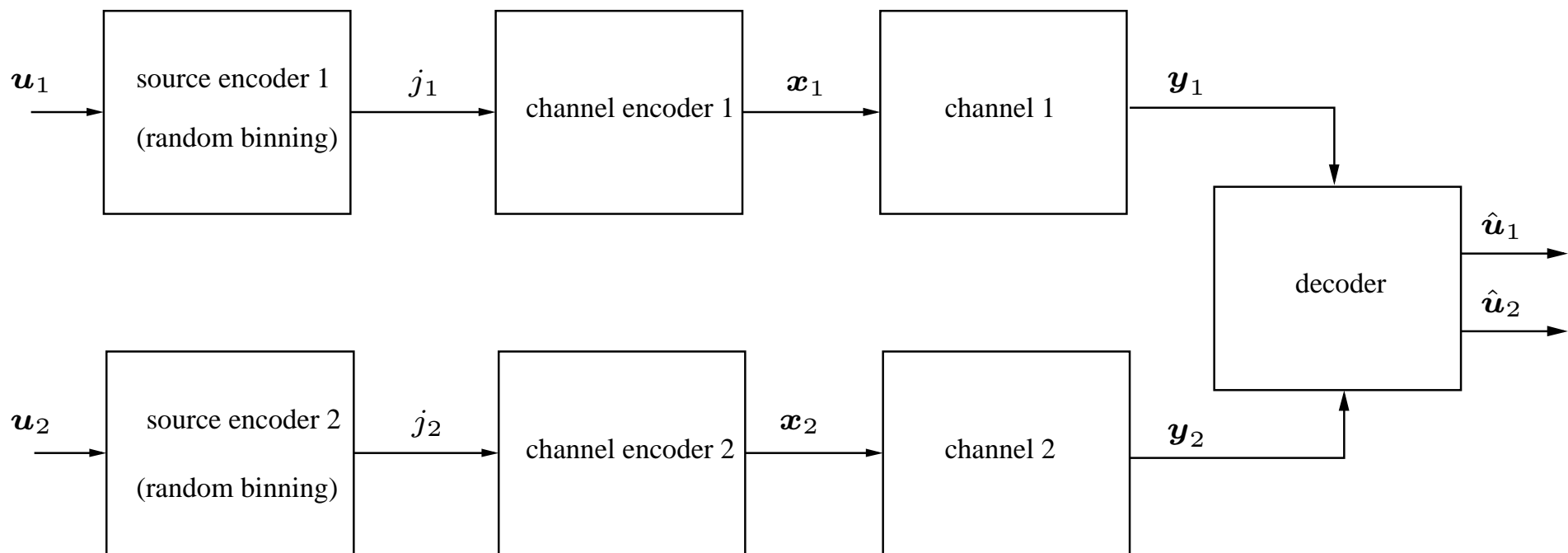
and finally, the universal decoding metric

$$\tilde{\mathbf{u}} = \arg \max_{\mathbf{u}} \left[ \hat{I}_{\text{LZ}}(\mathbf{x}[\mathbf{u}]; \mathbf{y}) - \hat{H}_{\text{LZ}}(\mathbf{u}|\mathbf{v}) \right].$$

The extension of Theorem 1 to FS sources/channels asserts that the above universal decoder achieves the same random-coding error exponent as the MAP decoder, in the spirit of [Ziv 1985].



## Setting 2



The optimal (MAP) decoder:

$$(\hat{u}_1, \hat{u}_2) = \arg \max_{u_1, u_2} P(u_1, u_2) W_1(y_1 | x_1[u_1]) W_2(y_2 | x_2[u_2]).$$

## Setting 2 (Cont'd)

Here, five types of pairwise errors should be handled differently:

- $u'_1 \neq u_1$  and  $u'_2 = u_2$ .
- $u'_2 \neq u_2$  and  $u'_1 = u_1$ .
- $u'_1 \neq u_1$  and  $u'_2 \neq u_2$ , but  $u'_2$  is in the bin of  $u_2$ .
- $u'_1 \neq u_1$  and  $u'_2 \neq u_2$ , but  $u'_1$  is in the bin of  $u_1$ .
- $u'_1 \neq u_1$ ,  $u'_2 \neq u_2$ , and neither  $u'_1$  nor  $u'_2$  are in the correct bins.

## Setting 2 (Cont'd)

Each type of error “demands” a different universal decoding metric:

- Errors of types 1 and 2 are handled the same as before:

$$\begin{aligned}f_1(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) &= R_1 \wedge \hat{I}(X_1; Y_1) - \hat{H}(U_1|U_2) \\f_2(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) &= R_2 \wedge \hat{I}(X_2; Y_2) - \hat{H}(U_2|U_1).\end{aligned}$$

- Errors of types 3 and 4 “would like to be handled” by:

$$\begin{aligned}f_3(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) &= R_1 \wedge \hat{I}(X_1; Y_1) + R_2 - \hat{H}(U_1, U_2) \\f_4(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) &= R_2 \wedge \hat{I}(X_2; Y_2) + R_1 - \hat{H}(U_1, U_2).\end{aligned}$$

- Error of type 5:

$$\begin{aligned}&f_5(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) \\&= [R_1 \wedge \hat{I}(X_1; Y_1) + R_2 \wedge \hat{I}(X_2; Y_2) - \hat{H}(U_1, U_2)]_+ + \\&[\hat{I}(X_1; Y_1) - R_1]_+ + [\hat{I}(X_2; Y_2) - R_2]_+.\end{aligned}$$

## Setting 2 (Cont'd)

But we need a **single** decoding metric and we have to confront all five types of errors at the same time!

Q: How can we integrate all these decoding metrics into one metric?

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But we need a **single** decoding metric and we have to confront all five types of errors at the same time!

Q: How can we integrate all these decoding metrics into one metric?

A: It turns out that this is achieved by taking the minimum of them.

Define

$$f_0(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) = \min_{1 \leq i \leq 5} f_i(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2).$$

Then, the universal decoder

$$(\tilde{\mathbf{u}}_1, \tilde{\mathbf{u}}_2) = \arg \max_{\mathbf{u}_1, \mathbf{u}_2} f_0(\mathbf{u}_1, \mathbf{u}_2, \mathbf{x}_1[\mathbf{u}_1], \mathbf{x}_2[\mathbf{u}_2], \mathbf{y}_1, \mathbf{y}_2)$$

achieves the same error exponent as the MAP decoder for Setting 2.

# Summary

- We extended Csiszár's universal JSC decoder in various directions:
  - Availability of decoder side information.
  - Separate source binning and channel coding.
  - Finite-state sources and channels.
- The extension to FS sources/channels can be applied also to Setting 2.
- Another extension: arbitrary sources/channels + given family of decoders.