# Finite-Length Analysis of Lossy Compression via Sparse Regression Codes

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## Motivation

- Recently, a new capacity-achieving type of codes, sparse regression codes (SPARCs), has been suggested (Joseph and Barron '12) for
  - reliable communication over memoryless channels
  - Iossy compression of memoryless and stationary sources

with continuous alphabets

- Current analysis is mostly asymptotic.
- This work is focused on the finite-length analysis of SPARCs for lossy compression of stationary memoryless sources.

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# Early Works on SPARCs

- A. Joseph and A. Barron, "Least squares superposition codes of moderate dictionary size are reliable at rates up to capacity," 2012
- A. Joseph and A. Barron, "Fast sparse superposition codes have near exponential error probability for R < C," 2014
- R. Venkataramanan, A. Joseph and S. Tatikonda, "Lossy compression via sparse linear regression: performance under minimum-distance encoding," 2014
- R. Venkataramanan, T. Sarkar and S. Tatikonda, "Lossy compression via sparse linear regression: computationally efficient encoding and decoding," 2014
- J. Barbier and F. Krzakala, "Approximate message-passing decoder and capacity-achieving sparse superposition codes," 2017

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# Lossy Compression Problem Setup



- Mean-squared distortion criterion  $\frac{1}{n} \|\mathbf{S} \hat{\mathbf{S}}\|^2$ .
- S is a memoryless stationary source with continuous alphabet.
- In particular: memoryless Gaussian source, for which  $D(R) = \sigma^2 e^{-2R}$ .

# Sparse Regression Codes



- Entries of **A** are i.i.d.  $\sim \mathcal{N}(0, \frac{1}{n})$ , known a-priori to encoder+decoder.
- A consists of *L* sections with *M* columns each.
- Entries of  $\beta$  are sparse: exactly one non-zero entry per section.
- Entries of  $\beta$  are pre-fixed.
- Codewords of the SPARC are the linear combinations  $\mathbf{A}\beta$ .

# Sparse Regression Codes



- Locations of non-zero entries {c<sub>1</sub>, c<sub>2</sub>,..., c<sub>L</sub>} in β are determined by the input bits.
- Decoder receives  $Y = \mathbf{A}\beta + Z$  and has to find  $\hat{\beta}$ .
- Total codewords  $M^L = \exp(nR) \Longrightarrow R = \frac{L \log M}{n}$

# Choosing M and L



For set values of n and R there are many valid choices for M and L

#### Example (Constant L = 1)

- Can be reliable for any rate R < C.
- But the size of **A** grows exponentially in *n*.

Practical choice:  $M = L^b$  for some b > 0

In this case,

$$nR = L \log M = bL \log L.$$

To solve *L* for given *n*, *R* and *b*, we make use of the Lambert *W*-function, which is the inverse relation of the function  $f(z) = ze^{z}$ .

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## Lambert W-Function

• Applying the Lambert W-function gives

$$L = \exp\left(W\left(\frac{nR}{b}\right)\right)$$

• In our work, we derived new tight upper and lower bounds.

$$W(x) = \log x - \log \log x + O\left(\frac{\log \log x}{\log x}\right).$$

•  $M = L^b$  implies that the size of the design matrix is  $ML \approx \left(\frac{n}{\log n}\right)^{b+1}$ .

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# Power Allocation



Non-zero coefficients of β are pre-fixed: c<sub>i</sub> = √nP<sub>i</sub> for i ∈ {1,..., L}.
Power restriction is met by Σ<sup>L</sup><sub>i=1</sub> P<sub>i</sub> = P.

#### **Examples**

• Flat:  $P_i = \frac{P}{n}$ 

• Exponentially decaying:  $P_i \propto e^{-ai/L}$  for some a > 0

# Lossy Compression with SPARCs



- Entries are i.i.d.  $\sim \mathcal{N}(0,1)$ .
- No power restriction ⇒ coefficients {c<sub>1</sub>,..., c<sub>L</sub>} are chosen to minimize distortion.
- $R = \frac{L \log M}{n}$ , with our setting where  $M = L^b$ , b > 0.

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# **Optimal Encoding**

#### **Optimal Encoder**

Minimum distance encoding:

$$\hat{eta} = \mathop{\mathrm{arg\,min}}_{eta} \|\mathbf{S} - \mathbf{A}eta\|^2,$$

where **S** is the source sequence and  $\|\cdot\|$  is the Euclidean norm.

#### Theorem (Venkataramanan and Tatikonda '17)

For a memoryless Gaussian source **S** with zero mean and variance  $\sigma^2$ , there exists a sequence of rate R SPARCs with

$$P\left(\frac{1}{n}\|\mathbf{S}-\mathbf{A}\beta\|^2 > D\right) < e^{-n(E^*(R,D)+O(1))},$$

where  $E^*(R, D)$  is the optimal error exponent

• Not feasible since the number of codewords is exponential in  $n_{\text{-}}$ 

# Successive Cancellation Encoding

Successive Cancellation Encoder [Venkataramanan et al., '14]

- $\bullet \ \mathsf{Set} \ \textbf{R}_0 = \textbf{S}$
- For  $i \in \{1, \ldots, L\}$ , choose the  $m_i$ -th column in section i with

$$m_i \triangleq \operatorname*{arg\,max}_{j:(i-1)M < j \le iM} \left\langle \mathbf{A}_j, \frac{\mathbf{R}_{i-1}}{\|\mathbf{R}_{i-1}\|} \right\rangle,$$

where  $\mathbf{A}_j$  is the j's column of  $\mathbf{A}$ .

• Define recursively the residual

$$\mathbf{R}_i = \mathbf{R}_{i-1} - c_i \mathbf{A}_{m_i}, \quad i \in \{1, \ldots, L\},$$

with 
$$c_i = \sigma \sqrt{\frac{2R}{L} \left(1 - \frac{2R}{L}\right)^{i-1}}$$

• After *L* steps,  $\beta$  is a sparse vector comprised of values  $\{c_i\}_1^L$  in indices  $\{m_i\}_1^L$  and zero elsewhere. The codeword is  $\mathbf{A}\beta$ .

# Successive Cancellation Encoding

#### Theorem (Venkataramanan et al., '14)

For an ergodic source **S** with mean 0 and variance  $\sigma^2$ , the encoding algorithm produces a codeword **A** $\beta$  that satisfies the following for large enough M and L,

$$P\left(\frac{1}{n}\|\mathbf{S}-\mathbf{A}\beta\|^2 > \sigma^2 e^{-2R}(1+e^R\Delta)^2\right) < p_0+p_1+p_2,$$

where  $\Delta = \delta_0 + 5R(\delta_1 + \delta_2)$  for any positive constants  $\delta_0$ ,  $\delta_1$  and  $\delta_2$  such that  $\Delta < \frac{1}{2}$ , and with

$$p_{0} = P\left(\left|\frac{|\mathbf{S}|}{\sigma} - 1\right| > \delta_{0}\right), \qquad p_{2} = \left(\frac{M^{2\delta_{2}}}{8\log M}\right)^{-L},$$

$$p_{1} = 2MLe^{-n\delta_{1}^{2}/8},$$
where  $|\cdot| = \frac{\|\cdot\|}{\sqrt{n}}$  is the scaled norm.

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# Successive Cancellation Encoding

#### Corollary

- If **S** is a memoryless Gaussian source sequence, the SPARC attains the distortion-rate function.
- For any distortion D greater than  $D(R) = \sigma^2 e^{-2R}$ , the probability of excess distortion decays exponentially in n.

#### Complexity

*L* stages involving *M* inner products of vectors of length  $n \Longrightarrow O(nML)$ The encoder is polynomial in *n* 

#### What is missing?

- No finite-length source sequence analysis
- Very loose bound

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## Preliminaries

#### Notation

Let  $X_1, \ldots, X_M$  be i.i.d. standard Gaussian random variables, then

$$Z_M = \max_{i \in 1, \dots, M} X_i$$
$$e_M = E[Z_M]$$

#### Lemma [Cramér '46]

$$e_M = \sqrt{2\log M} - \frac{\log\log M + \log 4\pi - 2\gamma}{2\sqrt{2\log M}} + O\left(\frac{\log\log M}{\log M}\right),$$

where  $\gamma$  is the Euler-Mascheroni constant

Preliminaries (cont.)

Upper Bound on  $e_M$ 

For all  $M \ge 1$ ,

$$e_M \leq \sqrt{2 \log M}$$

Proof: by invoking Jensen's inequality,

$$\exp(t e_M) \le E[\exp(t Z_M)] \le \sum_{i=1}^M E[\exp(t X_i)] = M \exp\left(\frac{1}{2}t^2\right)$$
$$\Rightarrow e_M \le \frac{\log M}{t} + \frac{t}{2},$$

for all t > 0. Minimization over t yields  $t = \sqrt{2 \log M}$ , which leads to the required result.

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# Preliminaries (cont.)



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# Modification of the Encoder

#### Reminder

In each step:

$$m_{i} = \arg \max_{j:(i-1)M < j \le iM} \left\langle \mathbf{A}_{j}, \frac{\mathbf{R}_{i-1}}{\|\mathbf{R}_{i-1}\|} \right\rangle,$$
$$\mathbf{R}_{i} = \mathbf{R}_{i-1} - c_{i}\mathbf{A}_{m_{i}},$$

with 
$$c_i = \sigma \sqrt{\frac{2R}{L} \left(1 - \frac{2R}{L}\right)^{i-1}}$$

Can we choose better coefficients  $\{c_1, \ldots, c_L\}$ , so that  $|\mathbf{R}_L|^2$  is smaller?

$$|\mathbf{R}_{i}|^{2} \approx |\mathbf{R}_{i-1}|^{2} \left(1 + \frac{c_{i}^{2}}{|\mathbf{R}_{i-1}|^{2}} - \frac{2c_{i}}{|\mathbf{R}_{i-1}|} \cdot \frac{e_{M}}{\sqrt{n}}\right)$$

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## Modification of the Encoder



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## New Main Theorem: Definitions

Definition:  $p_1$  and  $p_2$ For arbitrary  $\delta_1, \delta_2 > 0$ , let

$$p_1 = P\left(\frac{1}{L}\sum_{i=1}^{L}|\gamma_i| > \delta_1\right), \qquad p_2 = P\left(\frac{1}{L}\sum_{i=1}^{L}|\epsilon_i| > \delta_2\right),$$

where  $\{\gamma_i\}_{i=1}^{L}$  and  $\{\epsilon_i\}_{i=1}^{L}$  are defined by

$$\left\langle \left\langle \mathbf{A}_{m_i}, \frac{\mathbf{R}_{i-1}}{\|\mathbf{R}_{i-1}\|} \right\rangle = e_M(1+\epsilon_i),$$
  
 $|\mathbf{A}_{m_i}|^2 = 1 + \gamma_i.$ 

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## New Main Theorem

#### Theorem 1

For an ergodic source **S** with mean 0 and variance  $\sigma^2$ , the encoding algorithm produces a codeword **A** $\beta$  that satisfies the following for  $L \ge 10R$ ,

$$P\left(\frac{1}{n}\|\mathbf{S}-\mathbf{A}\beta\|^2 > \underbrace{\sigma^2\left(1-\frac{e_M^2}{n}\right)^L(1+w^L\Delta)^2}_{\alpha_L \wedge \alpha_L}\right) < p_0+p_1+p_2,$$

where  $\Delta = \delta_0 + 5R(\delta_1 + \delta_2)$  for any positive constants  $\delta_0$ ,  $\delta_1$  and  $\delta_2$  such that  $\Delta < \frac{1}{2}$ , and where  $w = 1 + \frac{e_M^2}{2}$ 

$$w=1+\frac{m}{2(n-e_M^2)}.$$

## Discussion

#### Main Message

- The modified coding scheme performs favorably for finite length codes.
- It is robust in the following sense: for any ergodic source, the proposed encoder achieves the optimal distortion-rate function of an i.i.d Gaussian source with the same variance.

#### Note

Asymptotically, the difference between the Gaussian distortion-rate function  $D(R) = \sigma^2 e^{-2R}$  and  $\alpha_{L,\Delta}$ , can be arbitrarily small, by choosing proper L and  $\Delta$ .

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• Better performance with the modified encoder for finite-length codes.

- Analysis of the modified encoder with finite L and M.
- The bound on the probability of excess distortion is substantially tighter.

#### Notation

Denote the multiplicative deviation of  $|\mathbf{R}_i|^2$  from its approximated value by  $\Delta_{i}$ ,

$$|\mathbf{R}_i|^2 = \sigma^2 \left(1 - rac{e_M^2}{n}
ight)^i (1 + \Delta_i)^2$$

Idea:

- Find a recursion for  $\Delta_i$
- Use this recursion to bound  $\Delta_L$  by taking the worst case scenario at each step
- Worst case scenario: the deviations  $\Delta_0$ ,  $\{\gamma_i\}_{i=1}^{L}$  and  $\{\epsilon_i\}_{i=1}^{L}$  are maximal and have the same sign

# Upper Bound on $p_0$ (General Case)

For all 
$$\delta \in (0, 1)$$
,  

$$p_0 \triangleq P\left(\left|\frac{|\mathbf{S}|}{\sigma} - 1\right| > \delta\right) \le \inf_{t>0} \left\{ e^{-n\left[t(1+\delta)^2 - \log M_{X^2}\left(\frac{t}{\sigma^2}\right)\right]} \right\} + \inf_{t>0} \left\{ e^{n\left[t(1-\delta)^2 + \log M_{X^2}\left(-\frac{t}{\sigma^2}\right)\right]} \right\},$$

where:

- X is a random variable with zero mean and finite variance  $\sigma^2$ .
- $M_{\chi^2}(t)$  is the moment-generating function of  $X^2$ .
- **S** is an i.i.d. source sequence of length *n*, with  $S_i \sim P_X$ .
- Proof: apply the Chernoff Bound twice
- The bound is exponentially decaying in n

# Exact Expression for $p_0$ (Gaussian Case)

Let **S** be an i.i.d. source sequence of length *n*, generated according to the Gaussian distribution  $\mathcal{N}(0, \sigma^2)$ , and let  $\delta \in (0, 1)$ . Then,

$$p_0 = 1 - ar{\gamma}\left(rac{n}{2},rac{n(1+\delta)^2}{2}
ight) + ar{\gamma}\left(rac{n}{2},rac{n(1-\delta)^2}{2}
ight)$$

where  $\bar{\gamma}$  is the incomplete Gamma function,

$$\bar{\gamma}(a,x) = \frac{1}{\Gamma(a)} \int_0^x t^{a-1} e^{-t} \mathrm{d}t.$$

Proof: follows from <sup>||S||<sup>2</sup></sup>/<sub>σ<sup>2</sup></sub> ~ χ<sup>2</sup>(n) (Chi-squared distributed with n degrees of freedom)

# Upper Bound on $p_1$

For all  $\delta \in (0, 1)$ ,

$$p_{1} \triangleq P\left(\frac{1}{L}\sum_{i=1}^{L}|\gamma_{i}| > \delta\right)$$

$$\leq \left(\inf_{0 < t < \frac{1}{2}} \left\{ \left(\frac{e^{t(1-\delta)}}{\sqrt{1+2t}}\right)^{n} \bar{\gamma}\left(\frac{n}{2}, \frac{n}{2} + nt\right) + \left(\frac{e^{-t(1+\delta)}}{\sqrt{1-2t}}\right)^{n} \left[1 - \bar{\gamma}\left(\frac{n}{2}, \frac{n}{2} - nt\right)\right] \right\} \right)^{L}$$

Reminders:

• 
$$\gamma_i = |\mathbf{A}_{m_i}|^2 - 1$$

•  $\bar{\gamma}(\cdot,\cdot)$  denotes the incomplete Gamma function

Upper Bound on  $p_1$  - Proof

Concept of proof:

- The columns of **A** are i.i.d.
- Chernoff's bound
- For any  $k \in \{1, ..., ML\}$ , we have  $\sum_{j=1}^{n} A_{j,k}^2 \sim \chi^2(n)$ , where  $A_{j,k}$  is the (j, k) entry in matrix **A**

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# Upper Bound on p2

For all  $\delta \in (0,1)$ ,

$$p_2 \triangleq P\left(\frac{1}{L}\sum_{i=1}^{L} |\epsilon_i| > \delta\right) \le \left(\inf_{t>0} \left\{ e^{-te_M\delta} \int_{-\infty}^{\infty} e^{t|z-e_M|} f_{Z_M}(z) \, \mathrm{d}z \right\} \right)^L,$$

where  $f_{Z_M}(\cdot)$  is the probability density function of  $Z_M$ .

• Reminder:  $\epsilon_i$  is the random variable which stands for the deviation

$$\max_{(i-1)M < j \le iM} \left\langle \mathsf{A}_j, \frac{\mathsf{R}_{i-1}}{\|\mathsf{R}_{i-1}\|} \right\rangle = e_M(1+\epsilon_i).$$

• Concept of proof: Chernoff bound after showing that  $\{\epsilon_i\}_{i=1}^{L}$  are i.i.d.

# Upper Bound on p<sub>2</sub>

#### Reminder

$$p_2 \leq \left(\inf_{t>0} \left\{ e^{-te_M\delta} \int_{-\infty}^{\infty} e^{t|z-e_M|} f_{Z_M}(z) \, \mathrm{d}z \right\} \right)^L$$

#### Efficient Computation of the Bound

The infimum in the bound of  $p_2$  is a minimum, and can be obtained numerically by the bisection method in the interval  $[0, t_M^*]$ , with

$$t_M^* = rac{1}{e_M} \log \left( rac{\sqrt{2}M}{\sqrt{\pi} f_{Z_M}(-2e_M)} 
ight)$$

Concept of proof:

- Convexity
- When  $t = t_M^*$ , the derivative is positive

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## The Complete Bound - Comparison

• The simulation was conducted as follows:

- Fix parameters R, b,  $\sigma^2$ ,  $\epsilon$
- Calculate the minimal n such that

$$P\left[|\mathbf{S}-\mathbf{A}\hat{\beta}|^2 > \sigma^2 e^{-2R}(1+\eta)\right] < \epsilon,$$

for a range of values  $\eta > 0$ 

• The following figures use R = 0.5,  $\sigma^2 = 1$  and  $\epsilon = 0.01$ 

The Complete Bound - Comparison



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The Complete Bound - Comparison



## Deviation from the Distortion-Rate Function

Bounds on  $D_{L,\Delta} \triangleq |\alpha_{L,\Delta} - \sigma^2 e^{-2R}|$ • For a large enough L,  $\frac{B\log\log L}{\log L} + O\left(\frac{\epsilon(L)\log\log L}{\log L}\right) \le D_{L,\Delta},$ where  $\epsilon(\cdot)$  is a non-negative function with  $\epsilon(L) \xrightarrow{} 0$  and B > 0. • If  $\Delta = \frac{A \log \log L}{b \log L}$  with a constant  $A > \frac{1}{4}$ , then for a large enough L,  $D_{L,\Delta} \leq \frac{C \log \log L}{\log L} + O\left(\frac{\epsilon(L) \log \log L}{\log L}\right),$ with C > 0.

# Deviation from the Distortion-Rate Function

Conclusions:

- The deviation from the distortion-rate function is upper bounded by  $O\left(\frac{\log \log L}{\log L}\right)$  with probability that tends to 1 as  $L \to \infty$ .
- Using Theorem 1, no significant improvement can be made to the upper bound.

#### Note

- The demand for the source sequence to be memoryless Gaussian is necessary to apply the upper bound on  $p_0$ .
- For other memoryless source distributions, the same results can be achieved under a suitable condition.

## Topics for Future Work

- Further Tightening the bound on the probability of excess distortion.
- Can the lossy compression scheme be generalized, in order to approach the rate-distortion function of non-Gaussian sources?
- Improving the tradeoff between complexity and performance of SPARCs .
- Channel coding via Spatially-coupled SPARCs shows better empirical results than with regular SPARCs. Finite blocklength analysis is currently missing, as well as lossy compression.

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# Thank You!

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# Modification to the Encoder

#### Lemma (Venkataramanan, Sarkar, Tatikonda '14)

Let  $\{\mathbf{A}_j\}_{j=1}^N$  be *N* mutually independent random vectors of length *n*, and suppose that the components of each vector are i.i.d. standard Gaussian random variables. Let **R** be a random vector independent of  $\{\mathbf{A}_j\}_{j=1}^N$  whose support lies on the *n*-dimensional unit sphere, i.e.,

$$\sum_{i=1}^{n} r_i^2 = 1$$

and let

$$T_j = \langle \mathbf{A}_j, \mathbf{R} \rangle$$

for every  $j \in \{1, ..., N\}$ . Then,  $\{T_j\}_{j=1}^N$  are i.i.d. standard Gaussian random variables which are independent of **R** 

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#### Notation

Denote the multiplicative deviation of  $|\mathbf{R}_i|^2$  from its approximated value by  $\Delta_i$ ,

$$|\mathbf{R}_i|^2 = \sigma^2 \left(1 - \frac{e_M^2}{n}\right)^i (1 + \Delta_i)^2$$

Idea: find a recursion for  $\Delta_i$ , and by it control the deviation after L steps,  $\Delta_L$ 

$$\begin{aligned} \mathbf{R}_{i}|^{2} &= |\mathbf{R}_{i-1}|^{2} + c_{i}^{2} |\mathbf{A}_{m_{i}}|^{2} - \frac{2c_{i}||\mathbf{R}_{i-1}||}{n} \left\langle \mathbf{A}_{m_{i}}, \frac{\mathbf{R}_{i-1}}{||\mathbf{R}_{i-1}||} \right\rangle \\ &\vdots \\ &= \sigma^{2} \left(1 - \frac{e_{M}^{2}}{n}\right)^{i} \left[ (1 + \Delta_{i-1})^{2} + \frac{e_{M}^{2}}{n - e_{M}^{2}} \left(\Delta_{i-1}^{2} + \gamma_{i} - 2\epsilon_{i}(1 + \Delta_{i-1})\right) \right] \end{aligned}$$

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$$\Rightarrow (1 + \Delta_i)^2 = (1 + \Delta_{i-1})^2 + \left(\frac{e_M^2}{n - e_M^2}\right) \left(\Delta_{i-1}^2 + \gamma_i - 2\epsilon_i(1 + \Delta_{i-1})\right)$$

Next step to bound  $\Delta_L$ : define event A to satisfy the following conditions,

• 
$$\left|\frac{|\mathbf{S}|}{\sigma} - 1\right| \le \delta_0$$
  
•  $\frac{1}{L} \sum_{i=1}^{L} |\gamma_i| \le \delta_1$   
•  $\frac{1}{L} \sum_{i=1}^{L} |\epsilon_i| \le \delta_2$ 

By the union bound,

$$P(\mathcal{A}^{\mathsf{c}}) \leq p_0 + p_1 + p_2$$

What remains: finding a bound on  $\Delta_L$  conditioning on event  $\mathcal{A}$ 

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#### Lemma

For  $L \geq 10R$ , conditioning on event A,

$$|\Delta_i| \leq |\Delta_0| w^i + \frac{2e_M^2}{n - e_M^2} \sum_{j=1}^i w^{j-j} (|\gamma_j| + |\epsilon_j|), \quad i \in \{1, \dots, L\}$$

The lemma is proved by induction, utilizing the recursion of  $\Delta_i$ , and taking the worst case scenario: the deviations  $\Delta_0$ ,  $\{\gamma_i\}_{i=1}^L$  and  $\{\epsilon_i\}_{i=1}^L$  are maximal and have the same sign

$$egin{aligned} \Rightarrow \Delta_L &\leq |\Delta_0| w^L + rac{2e_M^2}{n-e_M^2} \sum_{j=1}^L w^{L-j} (|\gamma_j|+|\epsilon_j|) \ &\leq w^L \left( \delta_0 + rac{2e_M^2 L}{n-e_M^2} \left( \delta_1 + \delta_2 
ight) 
ight) \ &\leq w^L \Delta \end{aligned}$$

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Upper Bound on  $p_2$  - Proof First show that  $\{\epsilon_i\}_{i=1}^{L}$  are i.i.d. Define

$$T_j^{(i)} \triangleq \left\langle \mathbf{A}_j, \frac{\mathbf{R}_{i-1}}{\|\mathbf{R}_{i-1}\|} \right\rangle, \quad j \in \{(i-1)M + 1, \dots, iM\}$$
$$T^{(i)} \triangleq \left(T_{(i-1)M+1}^{(i)}, \dots, T_{iM}^{(i)}\right)$$

The entries of A are i.i.d. ⇒ A<sub>j</sub> is independent of R<sub>i-1</sub> conditioned on {T<sup>(i-1)</sup>,...,T<sup>(1)</sup>, R<sub>0</sub>} for any j ∈ {(i-1)M+1,...,iM}
{T<sup>(i)</sup><sub>i</sub>} are i.i.d. standard Gaussian random variables (previous lemma)

$$\Rightarrow F_{\mathcal{T}^{(i)}|\mathcal{T}^{(i-1)},...,\mathcal{T}^{(1)},\mathbf{R}_{0}} = F_{\mathcal{T}^{(i)}} = \prod_{j=(i-1)M+1}^{iM} F_{\mathcal{T}^{(i)}_{j}},$$

and applying recursively,

$$F_{\mathbf{R}_0, \mathcal{T}^{(1)}, \dots, \mathcal{T}^{(L)}} = F_{\mathbf{R}_0} \prod_{i=1}^{L} F_{\mathcal{T}^{(i)}_{i=1}}$$

.

# Upper Bound on $p_2$ - Proof

Conclusions:

- $\{T^{(i)}\}$  are i.i.d. Gaussian random vectors
- They are independent of  $\mathbf{R}_0$
- Their components are i.i.d. standard Gaussian random variables The maximal values of  $\{T^{(i)}\}$ ,

$$V_i = \max_{(i-1)M < j \le iM} T_j^{(i)},$$

are i.i.d.  $\sim Z_M$ ; the deviations  $\{\epsilon_i\}_{i=1}^L$ , given by  $\epsilon_i = \frac{V_i}{e_M} - 1$ , are i.i.d.

- The Lemma follows from Chernoff's bound

But can this bound be computed efficiently?

#### Efficient Computation of the Upper Bound on $p_2$ The bound can be rewritten as

$$p_2 \leq \exp\left(-L \sup_{t>0} \left\{ t e_M \delta - \log\left(\int_{-\infty}^{\infty} e^{t|z-e_M|} f_{Z_M}(z) \, \mathrm{d}z\right) \right\} \right)$$

Define, for t > 0,

$$\begin{split} u_{\delta,M}(t) &\triangleq \frac{\mathrm{d}}{\mathrm{d}t} \left( \log \left( \int_{-\infty}^{\infty} e^{t|z-e_M|} f_{Z_M}(z) \, \mathrm{d}z \right) - t e_M \delta \right) \\ &= \frac{E \left[ |Z_M - e_M| \, e^{t|Z_M - e_M|} \right]}{E \left[ e^{t|Z_M - e_M|} \right]} - e_M \delta \end{split}$$

 $u_{\delta,M}(t)$  is monotonically increasing (Cauchy-Schwarz inequality)  $\Rightarrow$  the supremum can be obtained by the bisection method in the interval  $[0, t_M^*]$  for any  $t_M^* > 0$  such that  $u_{\delta,M}(t_M^*) \ge 0$ 

But does such  $t_M^*$  always exist?

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## Efficient Computation of the Upper Bound on $p_2$

If 
$$t^*_{\mathcal{M}} = \frac{1}{e_{\mathcal{M}}} \log \left( \frac{\sqrt{2}M}{\sqrt{\pi}f_{Z_{\mathcal{M}}}(-2e_{\mathcal{M}})} \right)$$
, then  $u_{\delta,\mathcal{M}}(t^*_{\mathcal{M}}) \geq 0$ 

Proof: it is enough to show that

$$E\left[\left|Z_{M}-e_{M}\right|e^{t_{M}^{*}\left|Z_{M}-e_{M}\right|}\right]-e_{M}E\left[e^{t_{M}^{*}\left|Z_{M}-e_{M}\right|}\right]\geq0$$

since  $\delta \in (0,1)$ . Analysis of the expression yields

$$\begin{split} E\left[|Z_M - e_M| \ e^{t_M^*|Z_M - e_M|}\right] &- e_M E\left[e^{t_M^*|Z_M - e_M|}\right] \\ &= \int_{-\infty}^{\infty} \left(|z - e_M| - e_M\right) e^{t|z - e_M|} f_{Z_M}(z) \, \mathrm{d}z \\ &\vdots \\ &\geq e_M^2 \left(f_{Z_M}(-2e_M) \ e^{te_M} - M\sqrt{\frac{2}{\pi}}\right) e^{te_M} \end{split}$$

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## First Item

#### Lemma

Let **S** be a memoryless Gaussian source sequence. If  $\Delta = \frac{A \log \log L}{b \log L}$  for some  $A > \frac{1}{4}$ , there exists a division of  $\Delta$  into  $\delta_0$ ,  $\delta_1$  and  $\delta_2$  such that

$$\lim_{L\to\infty}p_0+p_1+p_2=0$$

Previously,

$$p_0 + p_1 \le 2e^{-\frac{3n\delta_0^2}{4}} + 2MLe^{-\frac{n\delta_1^2}{8}}$$

 $\Rightarrow$  If  $\delta_0 = \delta_1 = \frac{1}{\log L}$ , then  $\lim_{L\to\infty} p_0 + p_1 = 0$ 

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For 
$$p_2$$
, if  $\delta_2 = \frac{A \log \log L}{b \log L}$ ,

$$p_{2} \leq \exp\left[-L\sup_{t>0}\left\{\left(te_{M}\delta_{2} - \log\left(\int_{-\infty}^{\infty} e^{t|z-e_{M}|}f_{Z_{M}}(z)\,\mathrm{d}z\right)\right)\right\}\right]$$
$$\leq \exp\left[-L\left(\frac{Ae_{M}^{2}\log\log M}{\log M} - \log\left(\int_{-\infty}^{\infty} e^{e_{M}|z-e_{M}|}f_{Z_{M}}(z)\,\mathrm{d}z\right)\right)\right]$$

For a large enough M, the integral can be bounded by  $C \cdot e_M$ , for a constant C > 0. From  $e_M \le \sqrt{2 \log M}$ ,

$$\log(e_M) + C \leq \frac{e_M^2 \log \log M}{4 \log M} + C',$$

and since  $A > \frac{1}{4}$ ,

$$\lim_{L\to\infty}p_2=0$$

# p<sub>0</sub> Comparison

The bound from previous works for the Gaussian case was

$$p_0 \leq 2e^{-\frac{3n\delta^2}{4}}$$

Comparison:

$(n, \delta)$	Exact <i>p</i> 0	Lemma 1	Previous
	(Lemma 2)	Bound	Bound
(10, 0.1)	0.66	> 1	> 1
(1000, 0.1)	$7.86 \cdot 10^{-6}$	$6.19 \cdot 10^{-5}$	$1.1 \cdot 10^{-3}$

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# p<sub>1</sub> Comparison

The upper bound on  $p_1$  in previous works was

$$p_1 \leq 2MLe^{-rac{n\delta^2}{8}}$$

Comparison:

$(n, L, M, \delta)$	Lemma 3	Looser Bound	Previous
	Bound	(Remark)	Bound
(10 <sup>2</sup> , 10, 10 <sup>2</sup> , 0.25)	$1.83 \cdot 10^{-4}$	$3.30\cdot10^{-4}$	> 1
(10 <sup>3</sup> , 10, 10 <sup>3</sup> , 0.10)	$1.57 \cdot 10^{-8}$	$1.83 \cdot 10^{-8}$	> 1

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# p<sub>2</sub> Comparison

The upper bound on  $p_2$  in previous works was

$$p_2 < \left(\frac{M^{2\delta}}{8\log M}\right)^{-L}$$

Comparison:

$(L, M, \delta)$	New Bound	Previous Bound
(10, 100, 0.25)	$1.95 \cdot 10^{-2}$	> 1
(10, 1000, 0.1)	$7.96 \cdot 10^{-1}$	> 1
(10, 10 <sup>4</sup> , 0.25)	$4.15 \cdot 10^{-11}$	$4.7 \cdot 10^{-2}$

#### Remark

The probability  $p_2$  is defined differently in previous works, since the deviations  $\{\epsilon_i\}_{i=1}^{L}$  are defined in relation to a different approximation

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## Lambert W Function

Known Bounds [Hoorfar and Hassani, '08]  
For every 
$$x \ge e$$
,  
 $\log x - \log \log x + \frac{1}{2} \frac{\log \log x}{\log x} \le W(x) \le \log x - \log \log x + \frac{e}{e-1} \frac{\log \log x}{\log x}$ 

Two bounds on  $\exp(W(x))$  can be derived from this bound:

• Applying exp(x) on both sides of the inequalities

• Using the identity 
$$\exp(W(x)) = \frac{x}{W(x)}$$

New Bounds Derived in This Work For every  $x \ge e$ ,

$$s(x) \leq e^{W(x)} \leq t(x),$$

with

$$s(x) \triangleq \frac{x}{\log t(x)}, \qquad t(x) \triangleq \frac{x}{\log x - \log \log \left(\frac{x}{v(x)}\right)},$$
  
 $v(x) \triangleq \log x - \log \left(\log \left(\frac{x}{\log x}\right) - \log \left(1 - \frac{\log \log x}{1 + \log x}\right)\right)$ 

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## Lambert W Function - Bound Comparison

Comparison Between the Bounds of exp(W(x))1.4 - New Bound --- Old Bound 1 1.35 ······ Old Bound 2 1.3 1.25 1.2 1.15 Old Bound 1 -Ratio exp(bound) 1.1 Old Bound 2 - uses 1.05  $\exp(W(x)) = \frac{x}{W(x)}$ 0.95 0.9 0.85 0.8 L 10<sup>3</sup> 104 105  $10^{1}$ 10<sup>2</sup> 106 X

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## Decoders

#### **Optimal Decoder**

Maximum likelihood decoder:

$$\hat{\boldsymbol{\beta}} = \arg\min_{\boldsymbol{\beta}} \|\boldsymbol{Y} - \boldsymbol{A}\boldsymbol{\beta}\|,$$

where Y is the output sequence of the channel

- With flat power allocation, for all R < C, the error probability decays exponentially in *n* [Joseph and Barron '12]
- Impractical: complexity grows exponentially in n

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## Adaptive Successive Hard-threshold Decoder

Idea: iteratively pick columns of  $\boldsymbol{\mathsf{A}}$  whose inner product with a residual is over a fixed threshold

#### Complexity

The complexity of the decoder is  $O(n^2 M) \Rightarrow$  Polynomial in n

With exponentially decaying power allocation,

Performance [Joseph and Barron '14]

For  $R < C_M$ ,

$$P_e \leq e^{-L(\mathcal{C}_M - R)^2 c_1},$$

where

$$\mathcal{C}_{M} \triangleq \mathcal{C}\left(1 - \frac{c_2}{\log M}\right)$$

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## Soft Decision Decoders

Two soft-decision decoders:

- Adaptive successive soft-decision decoder [Barron and Cho '12]
- Approximate message-passing (AMP) decoder [Barbier and Krzakala '17], [Rush, Grieg and Venkataramanan '17]

ldea: iteratively update the posterior probabilities of each entry of  $\beta$  being the true non-zero in its section

#### Performance

With exponential power allocation, for any R < C, the error probability of the soft-decision decoders decays exponentially in  $\frac{n}{(\log n)^c}$ , where c is a constant that depends on the scheme

Performance is empirically better than the hard-decision decoder

## Deviation from the Distortion-Rate Function

Reminder (from Theorem 1)

$$P\left(\frac{1}{n}\|\mathbf{S}-\mathbf{A}\beta\|^2 > \alpha_{L,\Delta}\right) < p_0 + p_1 + p_2$$

#### Definition

$$D_{L,\Delta} \triangleq \left| \alpha_{L,\Delta} - \sigma^2 e^{-2R} \right|$$

We showed that

 $\lim_{\Delta\to 0}\lim_{L\to\infty}D_{L,\Delta}=0$ 

Gal Livny (Technion)

Lossy Compression via SPARCs

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